## Saddle Points and Nonlinear Operators

Wataru Takahashi

## TOKYO INSTITUTE OF TECHNOLOGY DEPARTMENT OF MATHEMATICAL AND COMPUTING SCIENCES

Let H be a Hilbert space and let g be a proper lower semicontinuous convex function of H into  $(-\infty, \infty]$ . Then, we consider the convex minimization problem:

$$\min\{g(x): x \in H\}.\tag{(*)}$$

For such a g, we can define a multivalued operator  $\partial g$  on H by

$$\partial g(x) = \{x^* \in H : g(y) \ge g(x) + (x^*, y - x), y \in H\}$$

for all  $x \in H$ . Such a  $\partial g$  is said to be the *subdifferential* of g. An operator  $A \subset H \times H$  is *accretive*, if for  $(x_1, y_1), (x_2, y_2) \in A$ ,

$$(x_1 - x_2, y_1 - y_2) \ge 0.$$

If A is accretive, we can define, for each positive  $\lambda$ , the resolvent  $J_{\lambda} : R(I + \lambda A) \to D(A)$  by  $J_{\lambda} = (I + \lambda A)^{-1}$ . We know that  $J_{\lambda}$  is a nonexpansive mapping. An accretive operator  $A \subset H \times H$  is called *m*-accretive, if  $R(I + \lambda A) = H$  for all  $\lambda > 0$ . An m-accretive operator is equivalent to a maximal monotone operator in a Hilbert space. If  $g : H \to (-\infty, \infty]$  is a proper lower semicontinuous convex function, then  $\partial g$  is an m-accretive operator.

We know that one method for solving (\*) is the proximal point algorithm first introduced by Martinet. The proximal point algorithm is based on the notion of resolvent  $J_{\lambda}$ , i.e.,

$$J_{\lambda}x = \arg\min\bigg\{g(z) + \frac{1}{2\lambda}\|z - x\|^2 : z \in H\bigg\},\$$

introduced by Moreau. The proximal point algorithm is an iterative procedure, which starts at a point  $x_1 \in H$ , and generates recursively a sequence  $\{x_n\}$  of points  $x_{n+1} = J_{\lambda_n} x_n$ , where  $\{\lambda_n\}$  is a sequence of positive numbers, see, for instance, Rockafellar.

On the other hand, Halpern and Mann introduced the following iterative schemes to approximate a fixed point of a nonexpansive mapping T of H into itself:

$$x_{n+1} = \alpha_n x + (1 - \alpha_n) T x_n \quad \text{for } n \ge 1$$

and

$$x_{n+1} = \alpha_n x_n + (1 - \alpha_n) T x_n \quad \text{for } n \ge 1,$$

respectively, where  $x_1 = x \in H$  and  $\{\alpha_n\}$  is a sequence in [0, 1].

In this talk, motivated by their iterative methods for approximation of fixed points, we first prove weak and strong convergence theorems for resolvents of maximal monotone operators in a Hilbert space and a Banach space. Next, using these results, we consider the problem of finding a saddle point of a two variable function in a Hilbert space and a Banach space.